

26 marzo 2021 \vec{n} $d\sigma$

$$\iint_S \vec{F} \cdot \vec{n} \, d\sigma = \iint_D \vec{F} \circ \phi \frac{|\phi_x \wedge \phi_y|}{|\phi_x \wedge \phi_y|} dx dy$$

$$S = \{z = 2 - x^2 - y^2, z \geq 0\}$$

$$\vec{F} = (x^2, y^2, z), \quad \vec{n} \cdot \vec{e}_3 > 0$$

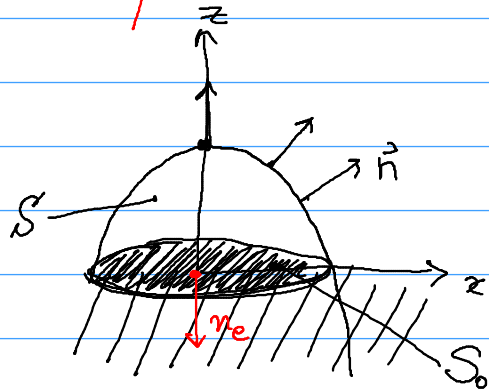
calcolo diretto

$$z = 2 - x^2 - y^2 \geq 0$$

$$D = \{x^2 + y^2 \leq 2\}$$

$$\phi: D \xrightarrow{\sim} S$$

$$(x, y) \rightarrow \begin{pmatrix} x \\ y \\ 2 - x^2 - y^2 \end{pmatrix}$$



$$\phi_x = (1, 0, -2x)$$

$$\phi_y = (0, 1, -2y)$$

$$\phi_x \wedge \phi_y = \begin{vmatrix} e_1 & e_2 & e_3 \\ 1 & 0 & -2x \\ 0 & 1 & -2y \end{vmatrix} = +2x e_1 + 2y e_2 + e_3$$

$$\iint_S \vec{F} \cdot \vec{n} \, d\sigma = \iint_D (2x^3 + 2y^3 + (2 - x^2 - y^2)) \, dx dy = \iint_D (2 - x^2 - y^2) \, dx dy =$$

$$= \int_0^{2\pi} \int_0^{\sqrt{2}} (2 - r^2) r \, dr d\theta = 2\pi \left(\left[r^2 \right]_0^{\sqrt{2}} - \left[\frac{r^4}{4} \right]_0^{\sqrt{2}} \right) = 2\pi (2 - 1)$$

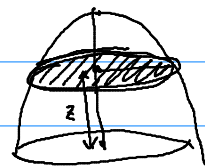
$$V = \{(x, y, z) : 0 \leq z \leq 2 - x^2 - y^2\} \quad \partial V = S \cup S_0$$

$$\iiint_V \text{div } F \, dx dy dz = \iint_{\partial V} \vec{F} \cdot \vec{n} \, d\sigma = \iint_S \vec{F} \cdot \vec{n} \, d\sigma + \iint_{S_0} \vec{F} \cdot \vec{n} \, d\sigma$$

\rightarrow è nullo

$$\text{div } F = 2x + 2y + 1$$

$$\iiint_V (2x + 2y + 1) \, dx dy dz = \iiint_V 1 \, dx dy dz = \int_0^2 \text{Area}(V_z) \, dz = \int_0^2 \pi R_z^2 \, dz = \pi \int_0^2 (2 - z)^2 \, dz =$$



$$= \pi \left[-\frac{(2-z)^2}{2} \right]_0^2 = 2\pi$$

$$\iint_S \vec{F} \cdot \vec{n} \, d\sigma \quad (\vec{n} \cdot \vec{e}_3 > 0)$$

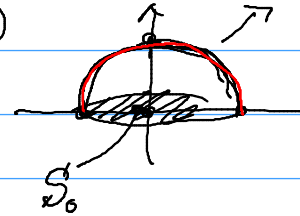
$$S = \{x^2 + y^2 + z^4 = 1, z \geq 0\}$$

$$\vec{n} = (1, 1, 1)$$

$$V = \{z \geq 0, x^2 + y^2 + z^4 \leq 1\}$$

$$\text{su } S_0, \vec{n}_e = (0, 0, -1)$$

$$\partial V = S \cup S_0$$



$$\circ \iint_V \text{div } F = \iint_S \vec{F} \cdot \vec{n}_e \, d\sigma + \iint_{S_0} \vec{F} \cdot \vec{n}_e \, d\sigma$$

$$D = \{x^2 + y^2 \leq 1\}$$

$$\iint_{S_0} \vec{F} \cdot \vec{n}_e = \iint_D -1 \, dx \, dy = -\pi$$

$$\iint_S \vec{F} \cdot \vec{n}_e = \pi$$

$$F(x, y, z) = \left(\frac{x}{r^3}, \frac{y}{r^3}, \frac{z}{r^3} \right)$$

$$r = \sqrt{x^2 + y^2 + z^2}$$

F è un campo radiale, a rinvio sferico, $\text{div } \vec{F} = 0$



$$\partial_x F = \frac{1}{r^3} + x \partial_x \left(\frac{1}{r^3} \right)$$

$$\partial_x r = \frac{x}{r}$$

$$= \frac{1}{r^3} - \frac{3x^2}{r^5}$$

$$\partial_x \left(\frac{1}{r^3} \right) = -\frac{3r^2 \partial_x r}{r^6} = -\frac{3x}{r^5}$$

$$\partial_y F = \frac{1}{r^3} - \frac{3y^2}{r^5}$$

$$\text{div } F = \partial_x F + \partial_y F + \partial_z F = \frac{3}{r^3} - \frac{\sqrt{x^2 + y^2 + z^2} \cdot r^2}{r^5} \equiv 0$$

$$\partial_z F = \frac{1}{r^3} - \frac{3z^2}{r^5}$$

$$F(x, y, z) = \left(\frac{x}{r^3}, \frac{y}{r^3}, \frac{z}{r^3} \right)$$

$$\vec{F}: \mathbb{R}^3 \setminus \{0\} \rightarrow \mathbb{R}^3$$

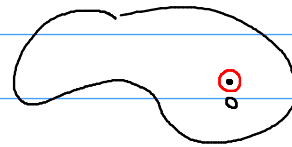
$$\iint_{\partial V} \vec{F} \cdot \vec{n}_e d\sigma = \begin{cases} 0 & \text{se } 0 \notin V \quad (1) \\ 4\pi & \text{se } 0 \in V \quad (2) \end{cases}$$

V aperto con bordo regolare (a tratti)

$$(1) \iint_{\partial V} \vec{F} \cdot \vec{n}_e d\sigma = \iiint_V \operatorname{div} \vec{F} dx dy dz = 0$$



$$(2) \iint_{\partial V} \vec{F} \cdot \vec{n}_e d\sigma = \iiint_V \operatorname{div} \vec{F} = 0$$



$$U = \bar{V} \setminus B_\delta(0)$$

$$\iint_{\partial V} \vec{F} \cdot \vec{n}_e - \iint_{\partial B_\delta(0)} \vec{F} \cdot \vec{n}_e$$

$$\text{su } \partial B_\delta(0): F \cdot n_e = \left(\frac{x}{r^3}, \frac{y}{r^3}, \frac{z}{r^3} \right) \cdot \left(\frac{x}{r}, \frac{y}{r}, \frac{z}{r} \right) = \frac{x^2 + y^2 + z^2}{r^4} = \frac{1}{r^2} = \frac{1}{\delta^2}$$

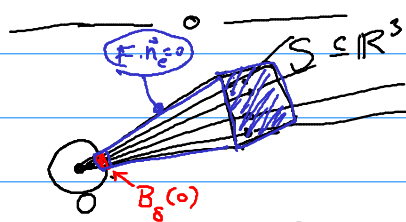
$$\iint_{\partial B_\delta(0)} \frac{1}{\delta^2} d\sigma = \frac{1}{\delta^2} 4\pi\delta^2 = 4\pi$$

da cui

$$\iint_{\partial V} \vec{F} \cdot \vec{n}_e = 4\pi$$

Angolo solido

V = "cono generato da S "
 un la toro
 angolo solido generato da S



superficie regolare

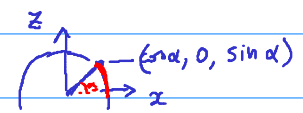
$$\iint_{\Sigma_\delta} \vec{F} \cdot \vec{n} = \iint_S \vec{F} \cdot \vec{n} d\sigma$$

misura dell'angolo solido V

$$\Sigma_\delta = \partial B_\delta(0) \cap V$$

Esercizio: Calcolare $\iint_{S_\alpha} \vec{F} \cdot \vec{n} d\sigma$

dove F è come sopra
 $S_\alpha = \left\{ \begin{array}{l} x^2 + y^2 + z^2 = a^2 \\ z \geq 0 \\ z \cos \alpha - x \sin \alpha < 0 \end{array} \right\}$



$$\varphi: \mathbb{R}_+ \longrightarrow \mathbb{R}$$

Esercizio: $\vec{x} = (x_1, x_2, \dots, x_n) \in \mathbb{R}^n$ $\vec{F}(x) = \varphi(r) \vec{x}$

$$r = \sqrt{\sum_{i=1}^n x_i^2}$$

Quale condizione deve soddisfare φ in modo che $\text{div } F = 0$

Rotore e NABLA - CALCOLO

$$\text{rot } \vec{F} = \begin{vmatrix} e_1 & e_2 & e_3 \\ \partial_1 & \partial_2 & \partial_3 \\ F_1 & F_2 & F_3 \end{vmatrix} = e_1 (\partial_2 F_3 - \partial_3 F_2) + e_2 (\partial_3 F_1 - \partial_1 F_3) + e_3 (\partial_1 F_2 - \partial_2 F_1)$$

Se $\varphi \in C^2$

- $\text{rot } (\nabla \varphi) = 0$
- $\text{div } (\text{rot } \vec{F}) = 0$

$\nabla \times (\nabla \varphi) = 0$	$\nabla \varphi = \text{grad } \varphi$
$\nabla \cdot (\nabla \times F) = 0$	$\vec{\nabla} \cdot \vec{F} = \text{div } F$
	$\vec{\nabla} \times \vec{F} = \text{rot } F$

↑ notazione dei fisici

• è $F_i = \partial_i \varphi$

$$\text{rot } (\nabla \varphi) = e_1 (\partial_2 \partial_3 \varphi - \partial_3 \partial_2 \varphi) + e_2 (\partial_3 \partial_1 \varphi - \partial_1 \partial_3 \varphi) + e_3 (\partial_1 \partial_2 \varphi - \partial_2 \partial_1 \varphi)$$

↑ è zero per Schwartz

$$\text{div } (\text{rot } F) = \partial_1 (\partial_2 F_3 - \partial_3 F_2) + \partial_2 (\partial_3 F_1 - \partial_1 F_3) + \partial_3 (\partial_1 F_2 - \partial_2 F_1)$$

$$= 0$$

Oss: Se $\vec{F}: \Omega \rightarrow \mathbb{R}^3$ campo C^1 t.c. $\text{rot } \vec{F} = 0 \Rightarrow F = \nabla \varphi$
 Ω sempl. connesso
 $\Omega \subset \mathbb{R}^3$
 (↓ $F dx + F_2 dy + F_3 dz$ è chiusa)

Domanda: Se $G: \Omega \rightarrow \mathbb{R}^3$ campo C^1 t.c. $\text{div } G = 0 \stackrel{?}{\Rightarrow} \exists \vec{F}: G = \text{rot } \vec{F}$

Risposta: In generale no, ma se $\Omega = I_1 \times I_2 \times I_3$ allora si

— 0 —

Controesempio: $G = \left(\frac{x}{r^3}, \frac{y}{r^3}, \frac{z}{r^3} \right)$ $\text{div} G = 0$ ma G non è un rotore

Dim Procedo per assurdo: suppongo $F: \mathbb{R}^3 \setminus \{0\} \rightarrow \mathbb{R}^3$

$\text{rot} F = G$

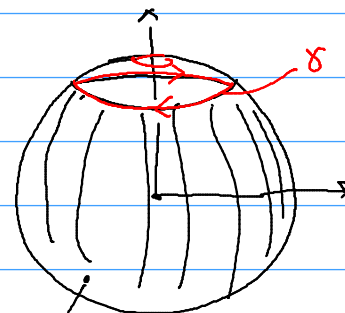
$\iint_{S_a} \vec{G} \cdot \vec{n}_e d\sigma = \iint_{S_a} \text{rot} F \cdot \vec{n}_e d\sigma = \oint_{\gamma} \vec{F} \cdot \vec{T} ds$ a → 1

Formula di Stokes

$\iint_{S_1} \vec{G} \cdot \vec{n}_e d\sigma \parallel 4\pi$

$= 0$

assurdo.



$S_a = \{x^2 + y^2 + z^2 = 1, z \leq a\}$
 $a \in (0, 1)$

se $G: \Omega \rightarrow \mathbb{R}^3$ campo C^1 , $\text{div} G = 0$ } $\implies \exists F \in C^2: G = \text{rot} F$
 $\Omega = I_1 \times I_2 \times I_3$

F si chiama potenziale vettore

Oss: se $F \approx \tilde{F}$ pot. vettori per $G \iff \text{rot}(F - \tilde{F}) = 0 \iff F = \tilde{F} + (\nabla \varphi)$

↳ la scelta di φ è arbitraria

$G = \text{rot} F$

$$\begin{cases} G_1 = \partial_2 F_3 - \partial_3 F_2 & (1) \\ G_2 = \partial_3 F_1 - \partial_1 F_3 & (2) \\ G_3 = \partial_1 F_2 - \partial_2 F_1 & (3) \end{cases}$$

$$\boxed{F_1 = 0} \quad (\text{ansatz})$$

$$G_2 = -\partial_1 F_3 \quad (2)$$

$$G_3 = \partial_1 F_2 \quad (3)$$

$$F_3(x, y, z) - \overbrace{F_3(x_0, y, z)}^{f(y, z)} = \int_{x_0}^x \partial_1 F_3(t, y, z) dt = - \int_{x_0}^x G_2(t, y, z) dt$$

$$F_3(x, y, z) = - \int_{x_0}^x G_2(t, y, z) dt + \cancel{f(y, z)}$$

$$F_2(x, y, z) = \int_{x_0}^x G_3(t, y, z) dt + \cancel{g(y, z)}$$

} le metto nella cond (1)

scelgo $f=0$

$$\boxed{G_1 = \partial_2 F_3 - \partial_3 F_2} \quad (1)$$

$$\cancel{G_1} = \partial_2 F_3 - \partial_3 F_1 = -\partial_2 \int_{x_0}^x G_2(t, y, z) dt - \partial_3 \int_{x_0}^x G_3(t, y, z) dt - \partial_3 g$$

$$= \int_{x_0}^x [-\partial_2 G_2(t, y, z) - \partial_3 G_3(t, y, z)] dt - \partial_3 g$$

$$\text{div } G = 0$$

$$\partial_1 G_1 + \partial_2 G_2 + \partial_3 G_3 = 0$$

$$= \int_{x_0}^x \partial_1 G_1(t, y, z) dt - \partial_3 g = \cancel{G_1(x, y, z)} - G_1(x_0, y, z) - \partial_3 g$$

Basta prendere $-\partial_3 g = G_1(x_0, y, z)$ cioè $g(y, z) = - \int_{z_0}^z G_1(x_0, y, s) ds$

Riassumendo il campo

$$\text{soddisfa } \boxed{\text{rot } \vec{F} = \vec{G}}$$

$$\begin{cases} F_1 = 0 \\ F_2 = \int_{x_0}^x G_3(t, y, z) dt - \int_{z_0}^z G_1(x_0, y, s) ds \\ F_3 = - \int_{x_0}^x G_2(t, y, z) dt \end{cases}$$

dove $x_0 \in \mathbb{I}_1$
 $z_0 \in \mathbb{I}_3$
 arbitrari

Esercizio: trovare un potenziale vettore per il campo $F = (1)$ (campo costante)

se $F = (F_1, F_2, F_3)$ è tale che $\text{rot } F = G$

$$\varphi(x, y, z) := \int_{x_0}^x F_1(t, y, z) dt \quad \varphi \text{ è ben definita}$$

$$\tilde{F} \doteq F - \nabla\varphi \quad \text{ha come prima componente} \quad F_1 - \partial_x\varphi = F_1 - F_1 = 0$$