

## The matrix exponential

We will now discuss some specific important matrix functions.

First one:

$$\expm(A) = I + A + \frac{1}{2}A^2 + \frac{1}{3!}A^3 + \dots$$

Useful to recall it: the solution of the ODE initial value problem

$$\frac{d}{dt}v(t) = Av(t), \quad v(0) = v_0$$

is  $v(t) = \expm(At)v_0$ .

**Proof:** we can differentiate term-by-term

$$v(t) = v_0 + tAv_0 + \frac{t^2}{2}A^2v_0 + \frac{t^3}{3}A^3v_0 + \dots$$

## How to compute $\text{expm}(A)$ ?

It is easy to come up with ways that turn out to be unstable.

[Moler, Van Loan, "Nineteen dubious ways to compute the exponential of a matrix", '78 & '03].

**Example** truncated Taylor series,  $I + A + \frac{1}{2}A^2 + \frac{1}{6}A^3 \dots + \frac{1}{k!}A^k$ .

(See example in the previous slide set.)

## Growth in matrix powers

The main problem in computing matrix power series: intermediate growth of coefficients.

**Example** Even on a nilpotent matrix, entries may grow.

$$A = \begin{bmatrix} 0 & 10 & & \\ & 0 & 10 & \\ & & 0 & 10 \\ & & & 0 \end{bmatrix}, \quad A^2 = \begin{bmatrix} 0 & 0 & 100 & \\ & 0 & 0 & 100 \\ & & 0 & 0 \\ & & & 0 \end{bmatrix}, \quad A^3 = \begin{bmatrix} 0 & 0 & 0 & 1000 \\ & 0 & 0 & 0 \\ & & 0 & 0 \\ & & & 0 \end{bmatrix}.$$

Typical behavior for non-normal matrices. Growth + cancellation = trouble.

(For normal matrices,  $\|A^k\| = \|A\|^k = |\lambda_{\max}|^k$ .)

## “Humps”

Similarly,  $\exp(tA)$  may grow for small values of  $t$  before ‘settling down’.

### Example

```
>> A = [-0.97 25; 0 -0.3];  
>> t = linspace(0,20,100);  
>> for i = 1:length(t); y(i) = norm(expm(t(i)*A)); end  
>> plot(t, y)
```

For the same reason, it is also a bad idea to use an ODE solver on

$$X'(t) = AX(t), \quad X(0) = I;$$

**Nice fact:** explicit Euler produces  $\exp(At) \approx (I + \frac{t}{n}A)^n$ .

## Padé approximants

Padé approximants to the exponential (in  $x = 0$ ) are known explicitly.

### Padé approximants to $\exp(x)$

$|\exp(x) - N_{pq}(x)/D_{pq}(x)| = O(x^{p+q+1})$ , where

$$\begin{aligned} N_{pq}(x) &= \sum_{j=0}^p \frac{(p+q-j)! p!}{(p+q)! j! (p-j)!} x^j \\ D_{pq}(x) &= \sum_{j=0}^q \frac{(p+q-j)! q!}{(p+q)! j! (q-j)!} (-x)^j. \end{aligned}$$

$$\exp(A) \approx (D_{pq}(A))^{-1} N_{pq}(A).$$

The main danger comes from  $D_{pq}(A)^{-1}$ .

For large  $p, q$ ,  $D_{pq}(A) \approx \exp(-\frac{1}{2}A)$ .  $\kappa(D_{pq}(A)) \approx \frac{e^{-\frac{1}{2}\lambda_{\min}}}{e^{-\frac{1}{2}\lambda_{\max}}}$ .

## Backward error of Padé approximants

Are Padé approximants reliable when  $\|A\|$  is small, at least?

**Recall:** perfect scalar approximation does not imply good matrix approximation.

Let  $H = f(A)$ , where  $f(x) = \log(e^{-x} \frac{N_{pq}(x)}{D_{pq}(x)})$ .  $H$  is a matrix function, so it commutes with  $A$ .

(Note that  $e^{-x} \frac{N_{pq}(x)}{D_{pq}(x)} = 1 + O(x^{p+q+1})$ , so the log exists for  $x$  sufficiently small).

One has  $\exp(H) = \exp(-A)(D_{pq}(A))^{-1}N_{pq}(A)$ , so

$$(D_{pq}(A))^{-1}N_{pq}(A) = \exp(A)\exp(H) = \exp(A + H)$$

(since  $A$  and  $H$  commute).

We can regard  $H$  as a sort of 'backward error': the Padé approximant  $(D_{pq}(A))^{-1}N_{pq}(A)$  is the exact exponential of a certain perturbed matrix  $A + H$ .

Can one bound  $\frac{\|H\|}{\|A\|}$ ?

## Bounding $\|H\|$

$H = f(A)$ , where  $f(x) = \log\left(e^{-x} \frac{N_{pq}(x)}{D_{pq}(x)}\right)$ .

$f$  is analytic, so  $f(x) = c_1 x^{p+q+1} + c_2 x^{p+q+2} + c_3 x^{p+q+3} + \dots$

$$H = f(A) = c_1 A^{p+q+1} + c_2 A^{p+q+2} + c_3 A^{p+q+3} + \dots$$

$$\|H\| \leq |c_1| \|A\|^{p+q+1} + |c_2| \|A\|^{p+q+2} + |c_3| \|A\|^{p+q+3} + \dots$$

All these quantities can be computed, explicitly or with Mathematica (but it's a lot of work).

Luckily, someone did it for us. For instance:

[Higham book '08, p. 244]

If  $p = q = 13$  and  $\|A\| \leq 5.4$ , then  $\frac{\|H\|}{\|A\|} \leq \mathbf{u}$  (machine precision).

Degree 13 achieves a good ratio between accuracy and number of required operations (with Paterson–Stockmayer + noting that numerator and denominator are of the form  $p(x^2) \pm xq(x^2)$ .)

Evaluating  $N_{13,13}$  and  $D_{13,13}$  requires 6 matmuls.

## Scaling and squaring

What if  $\|A\| > 5.4$ ? Trick:  $\exp(A) = (\exp(\frac{1}{s}A))^s$ .

### Algorithm (scaling and squaring)

1. Find  $s = 2^k$  such that  $\|\frac{1}{s}A\| \leq 5.4$ .
2. Compute  $F = D_{13,13}(B)^{-1}N_{13,13}(B)$ , where  $D_{13,13}$  and  $N_{13,13}$  are given polynomials and  $B = \frac{1}{s}A$ .
3. Compute  $F^{2^k}$  by repeated squaring.

This is Matlab's `expm`, currently (more or less — approximants of degree smaller than 13 are used in some cases).



## Is scaling and squaring stable?

Note that 'humps' may still give problems:  $\exp(B)$  may be much larger than  $\exp(A) = \exp(B)^{2^k}$ , leading to cancellation in the squares.

Is scaling and squaring stable for all matrices? Numerically it seems so, but no definitive answer.